

Bull. Korean Math. Soc. **50** (2013), No. 3, pp. 787–799
<http://dx.doi.org/10.4134/BKMS.2013.50.3.787>

SECTIONAL CURVATURES OF THE SIEGEL-JACOBI SPACE

JAE-HYUN YANG, YOUNG-HOON YONG, SU-NA HUH, JUNG-HEE SHIN,
AND GIL-HONG MIN

Reprinted from the
Bulletin of the Korean Mathematical Society
Vol. 50, No. 3, May 2013

©2013 The Korean Mathematical Society

SECTIONAL CURVATURES OF THE SIEGEL-JACOBI SPACE

JAE-HYUN YANG, YOUNG-HOON YONG, SU-NA HUH, JUNG-HEE SHIN,
 AND GIL-HONG MIN

ABSTRACT. In this paper, we compute the sectional curvatures and the scalar curvature of the Siegel-Jacobi space $\mathbb{H}_1 \times \mathbb{C}$ of degree 1 and index 1 explicitly.

1. Introduction

For a given fixed positive integer n , we let

$$\mathbb{H}_n := \{Z \in \mathbb{C}^{(n,n)} \mid Z = {}^t Z, \operatorname{Im} Z > 0\}$$

be the Siegel upper half plane of degree n and let

$$Sp(n, \mathbb{R}) = \{M \in \mathbb{R}^{(2n,2n)} \mid {}^t M J_n M = J_n\}$$

be the symplectic group of degree n , where $F^{(k,l)}$ denotes the set of all $k \times l$ matrices with entries in a commutative ring F for two positive integers k and l , ${}^t M$ denotes the transpose of a matrix M , $\operatorname{Im} Z$ denotes the imaginary part of Z and

$$J_n = \begin{pmatrix} 0 & I_n \\ -I_n & 0 \end{pmatrix}.$$

Here I_n denotes the $n \times n$ identity matrix. It is easy to see that $Sp(n, \mathbb{R})$ acts on \mathbb{H}_n transitively by

$$(1.1) \quad M \cdot Z := (AZ + B)(CZ + D)^{-1},$$

where $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in Sp(n, \mathbb{R})$ and $Z \in \mathbb{H}_n$.

For two positive integers n and m , we consider the Heisenberg group

$$H_{\mathbb{R}}^{(n,m)} := \{(\lambda, \mu; \kappa) \mid \lambda, \mu \in \mathbb{R}^{(m,n)}, \kappa \in \mathbb{R}^{(m,m)}, \kappa + \mu {}^t \lambda \text{ symmetric}\}$$

endowed with the following multiplication law

$$(\lambda, \mu; \kappa) \circ (\lambda', \mu'; \kappa') := (\lambda + \lambda', \mu + \mu'; \kappa + \kappa' + \lambda {}^t \mu' - \mu {}^t \lambda').$$

Received February 23, 2012; Revised May 22, 2012.

2010 *Mathematics Subject Classification*. Primary 32Q15, 32M10, 53C30.

Key words and phrases. Siegel-Jacobi space, sectional curvatures, scalar curvature.

This work was supported by Basic Science Program through the National Research Foundation of Korea(NRF) funded by the Ministry of Education, Science and Technology (43338-01).

We define the semidirect product of $Sp(n, \mathbb{R})$ and $H_{\mathbb{R}}^{(n,m)}$

$$G_{n,m}^J := Sp(n, \mathbb{R}) \ltimes H_{\mathbb{R}}^{(n,m)}$$

endowed with the following multiplication law

$$\left(M, (\lambda, \mu; \kappa)\right) \cdot \left(M', (\lambda', \mu'; \kappa')\right) := \left(MM', (\tilde{\lambda} + \lambda', \tilde{\mu} + \mu'; \kappa + \kappa' + \tilde{\lambda}^t \mu' - \tilde{\mu}^t \lambda')\right)$$

with $M, M' \in Sp(n, \mathbb{R}), (\lambda, \mu; \kappa), (\lambda', \mu'; \kappa') \in H_{\mathbb{R}}^{(n,m)}$ and $(\tilde{\lambda}, \tilde{\mu}) := (\lambda, \mu)M'$.

We call this group $G_{n,m}^J$ the *Jacobi group* of degree n and index m . It is easy to see that $G_{n,m}^J$ acts on $\mathbb{H}_n \times \mathbb{C}^{(m,n)}$ transitively by

$$(1.2) \quad \left(M, (\lambda, \mu; \kappa)\right) \cdot (Z, W) := \left(M \cdot Z, (W + \lambda Z + \mu)(CZ + D)^{-1}\right),$$

where $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in Sp(n, \mathbb{R}), (\lambda, \mu; \kappa) \in H_{\mathbb{R}}^{(n,m)}$ and $(Z, W) \in \mathbb{H}_n \times \mathbb{C}^{(m,n)}$.

The homogeneous space $\mathbb{H}_n \times \mathbb{C}^{(m,n)}$ is called the *Siegel-Jacobi space* of degree n and index m . We refer to [3, 5, 6, 7, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18] for more details on materials related to the Siegel-Jacobi space.

In [14], the author proved that for any two positive real numbers A and B , the following metric

$$(1.3) \quad \begin{aligned} ds_{n,m;A,B}^2 &= A \sigma\left(Y^{-1} dZ Y^{-1} d\bar{Z}\right) \\ &+ B \left\{ \sigma\left(Y^{-1} {}^t V V Y^{-1} dZ Y^{-1} d\bar{Z}\right) + \sigma\left(Y^{-1} {}^t (dW) d\bar{W}\right) \right. \\ &\left. - \sigma\left(V Y^{-1} dZ Y^{-1} {}^t (d\bar{W})\right) - \sigma\left(V Y^{-1} d\bar{Z} Y^{-1} {}^t (dW)\right) \right\} \end{aligned}$$

is a Riemannian metric on the Siegel-Jacobi space $\mathbb{H}_n \times \mathbb{C}^{(m,n)}$ which is invariant under the action (1.2) of the Jacobi group $G_{n,m}^J$, where $Z = X + iY \in \mathbb{H}_n, W = U + iV \in \mathbb{C}^{(m,n)}$ with $Z = (z_{ij}), W = (w_{kl})$ and X, Y, U, V real, we put

$$dZ = (dz_{ij}), \quad d\bar{Z} = (d\bar{z}_{ij}), \quad dW = (dw_{kl}), \quad d\bar{W} = (d\bar{w}_{kl})$$

and $\sigma(A)$ denotes the trace of a square matrix A . Also he computed the Laplace-Beltrami operator of the Siegel-Jacobi space $(\mathbb{H}_n \times \mathbb{C}^{(m,n)}, ds_{n,m;A,B}^2)$ explicitly.

In this paper, we consider the case $n = 1$ and $m = 1$. In this case, we have a Riemannian metric

$$(1.4) \quad \begin{aligned} ds_{1,1;A,B}^2 &= A \frac{dx^2 + dy^2}{y^2} + B \left\{ \frac{v^2}{y^3} (dx^2 + dy^2) + \frac{1}{y} (du^2 + dv^2) - \frac{2v}{y^2} (dxdu + dydv) \right\} \end{aligned}$$

on $\mathbb{H}_1 \times \mathbb{C}$ which is invariant under the action (1.2) of the Jacobi group $G_{1,1}^J = SL(2, \mathbb{R}) \ltimes H_{\mathbb{R}}^{(1,1)}$, where $z = x + iy \in \mathbb{H}_1$ and $w = u + iv \in \mathbb{C}$ with x, y, u, v real coordinates. We also refer to [1] and [4] for the metric (1.4). According to

Theorem 1.2 in [14], we see that the Laplace-Beltrami operator $\Delta_{1,1;A,B}$ of the Siegel-Jacobi space $(\mathbb{H}_1 \times \mathbb{C}, ds_{1,1;A,B}^2)$ is given by

$$(1.5) \quad \Delta_{1,1;A,B} = \frac{1}{A} \left\{ y^2 \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) + v^2 \left(\frac{\partial^2}{\partial u^2} + \frac{\partial^2}{\partial v^2} \right) + 2yv \left(\frac{\partial^2}{\partial x \partial u} + \frac{\partial^2}{\partial y \partial v} \right) \right\} + \frac{y}{B} \left(\frac{\partial^2}{\partial u^2} + \frac{\partial^2}{\partial v^2} \right).$$

The purpose of this paper is to compute the sectional curvatures of the Siegel-Jacobi space $(\mathbb{H}_1 \times \mathbb{C}, ds_{1,1;A,B}^2)$ explicitly. We will prove that the scalar curvature $r(p)$ of $(\mathbb{H}_1 \times \mathbb{C}, ds_{1,1;A,B}^2)$ is constant, precisely, $r(p) = -\frac{3}{A}$ for all $p \in \mathbb{H}_1 \times \mathbb{C}$.

This paper is organized as follows. In Section 2, we compute the Christoffel symbols Γ_{ij}^k of the Siegel-Jacobi space $(\mathbb{H}_1 \times \mathbb{C}, ds_{1,1;A,B}^2)$ explicitly. In Section 3, we compute the sectional curvatures of the Siegel-Jacobi space $(\mathbb{H}_1 \times \mathbb{C}, ds_{1,1;A,B}^2)$ explicitly. We prove that the scalar curvature of the Siegel-Jacobi space $(\mathbb{H}_1 \times \mathbb{C}, ds_{1,1;A,B}^2)$ is given by $-\frac{3}{A}$ and that the scalar curvature is independent of the choice of B . In the final section, we discuss the invariant Riemannian metrics of the Siegel-Jacobi disk $\mathbb{D} \times \mathbb{C}$ and their Laplace-Beltrami operators.

Notations: We denote by \mathbb{R} and \mathbb{C} the field of real numbers, and the field of complex numbers respectively. The symbol “:=” means that the expression on the right is the definition of that on the left. For two positive integers k and l , $F^{(k,l)}$ denotes the set of all $k \times l$ matrices with entries in a commutative ring F . For a square matrix $A \in F^{(k,k)}$ of degree k , $\sigma(A)$ denotes the trace of A . For any $M \in F^{(k,l)}$, tM denotes the transpose matrix of M . I_n denotes the identity matrix of degree n .

2. Preliminaries

For brevity, we write $M := \mathbb{H}_1 \times \mathbb{C}$. Then M is a four dimensional Riemannian manifold with a metric ds^2 given by (1.4). We denote by $C^\infty(M)$ and $\mathcal{X}(M)$ be the algebra of all C^∞ functions on M and the algebra of all C^∞ vector fields on M respectively. It is well known that there exists a uniquely determined Riemannian connection ∇ on M (cf. [2], p. 314). That is, the connection ∇ is a mapping $\nabla : \mathcal{X}(M) \times \mathcal{X}(M) \rightarrow \mathcal{X}(M)$, denoted by $\nabla(X, Y) = \nabla_X Y$ which satisfies the following properties (R1)-(R4): For all $f, g \in C^\infty(M)$ and $X, Y, Z, W \in \mathcal{X}(M)$,

- (R1) $\nabla_{fX+gY} Z = f(\nabla_X Z) + g(\nabla_Y Z)$,
- (R2) $\nabla_X (fY + gZ) = f(\nabla_X Y) + g(\nabla_X Z) + (Xf)Y + (Xg)Z$,
- (R3) $[X, Y] = \nabla_X Y - \nabla_Y X$ (symmetry), and
- (R4) $X(g(Y, Z)) = g(\nabla_X Y, Z) + g(Y, \nabla_X Z)$,

where $g(Y, Z)$ denoted the inner product determined by the Riemannian metric ds^2 on M .

Now we fix a local coordinate x, y, u, v with $z = x + iy$ and $w = u + iv$. Then the smooth vector fields

$$E_1 := \frac{\partial}{\partial x}, \quad E_2 := \frac{\partial}{\partial y}, \quad E_3 := \frac{\partial}{\partial u} \quad \text{and} \quad E_4 := \frac{\partial}{\partial v}$$

form a local frame fields on M . We recall that the *Christoffel symbols* Γ_{ij}^k ($1 \leq i, j, k \leq 4$) are defined by

$$(2.1) \quad \nabla_{E_i} E_j := \sum_{k=1}^4 \Gamma_{ij}^k E_k, \quad 1 \leq i, j \leq 4.$$

According to (1.4), the matrix form $g = (g_{ij})$ of the metric $ds_{1,1;A,B}^2$ is of the form

$$(2.2) \quad g = (g_{ij}) = \begin{pmatrix} \frac{Ay + Bv^2}{y^3} & 0 & -\frac{Bv}{y^2} & 0 \\ 0 & \frac{Ay + Bv^2}{y^3} & 0 & -\frac{Bv}{y^2} \\ -\frac{Bv}{y^2} & 0 & \frac{B}{y} & 0 \\ 0 & -\frac{Bv}{y^2} & 0 & \frac{B}{y} \end{pmatrix}.$$

Then it is easy to see that $\det(g_{ij}) = A^2 B^2 y^{-6}$ and the inverse matrix $g^{-1} := (g^{ij})$ of $g = (g_{ij})$ is given by

$$(2.3) \quad g^{-1} = (g^{ij}) = \begin{pmatrix} \frac{y^2}{A} & 0 & \frac{yv}{A} & 0 \\ 0 & \frac{y^2}{A} & 0 & \frac{yv}{A} \\ \frac{yv}{A} & 0 & \frac{Ay + Bv^2}{AB} & 0 \\ 0 & \frac{yv}{A} & 0 & \frac{Ay + Bv^2}{AB} \end{pmatrix}.$$

Lemma 2.1. *For all $i, j, k, \Gamma_{ij}^k = \Gamma_{ji}^k$. The Christoffel symbols Γ_{ij}^k 's ($1 \leq i, j, k \leq 4$) are given by*

$$\begin{aligned} \Gamma_{11}^2 &= \frac{2Ay + Bv^2}{2Ay^2}, & \Gamma_{12}^1 &= \Gamma_{22}^2 = -\frac{2Ay + Bv^2}{2Ay^2} \\ \Gamma_{11}^4 &= \frac{Bv^3}{2Ay^3}, & \Gamma_{12}^3 &= \Gamma_{22}^4 = -\frac{Bv^3}{2Ay^3} \\ \Gamma_{14}^1 &= \Gamma_{23}^1 = \Gamma_{24}^2 = \Gamma_{33}^4 = \frac{Bv}{2Ay}, & \Gamma_{13}^2 &= \Gamma_{34}^3 = \Gamma_{44}^4 = -\frac{Bv}{2Ay} \end{aligned}$$

$$\begin{aligned}\Gamma_{13}^4 &= \frac{Ay - Bv^2}{2Ay^2}, & \Gamma_{14}^3 &= \Gamma_{23}^3 = \Gamma_{24}^4 = -\frac{Ay - Bv^2}{2Ay^2} \\ \Gamma_{33}^2 &= \frac{B}{2A}, & \Gamma_{44}^2 &= \Gamma_{34}^1 = -\frac{B}{2A}\end{aligned}$$

and all other $\Gamma_{ij}^k = 0$.

Proof. The first statement follows immediately from the symmetry relation (R3). We recall (cf. [2], p. 318 or [8], p. 210) that

$$(2.4) \quad \Gamma_{ij}^k = \frac{1}{2} \sum_{s=1}^4 g^{ks} (E_j g_{si} - E_s g_{ij} + E_i g_{js})$$

for all i, j, k . By an easy computation, we get all Γ_{ij}^k . \square

We define the functions

$$(2.5) \quad h_A := \frac{y^{\frac{3}{2}}}{(Ay + Bv^2)^{\frac{1}{2}}}, \quad h_B := \frac{\sqrt{B} y v}{\sqrt{A} (Ay + Bv^2)^{\frac{1}{2}}}, \quad h_C := \frac{(y + v^2)^{\frac{1}{2}}}{\sqrt{AB}}.$$

An easy computation gives the following:

Lemma 2.2.

$$\begin{aligned}\frac{\partial h_A}{\partial y} &= \frac{y^{\frac{1}{2}}(2Ay + 3Bv^2)}{2(Ay + Bv^2)^{\frac{3}{2}}}, & \frac{\partial h_B}{\partial y} &= \frac{\sqrt{B} v (Ay + 2Bv^2)}{2\sqrt{A} (Ay + Bv^2)^{\frac{3}{2}}}, \\ \frac{\partial h_C}{\partial y} &= \frac{\sqrt{A}}{2\sqrt{B} (Ay + Bv^2)^{\frac{1}{2}}}, & \frac{\partial h_A}{\partial v} &= -\frac{B y^{\frac{3}{2}} v}{(Ay + Bv^2)^{\frac{3}{2}}}, \\ \frac{\partial h_B}{\partial v} &= \frac{\sqrt{AB} y^2}{(Ay + Bv^2)^{\frac{3}{2}}}, & \frac{\partial h_C}{\partial v} &= \frac{\sqrt{B} v}{\sqrt{A} (Ay + Bv^2)^{\frac{1}{2}}}\end{aligned}$$

and

$$\frac{\partial h_A}{\partial x} = \frac{\partial h_B}{\partial x} = \frac{\partial h_C}{\partial x} = \frac{\partial h_A}{\partial u} = \frac{\partial h_B}{\partial u} = \frac{\partial h_C}{\partial u} = 0.$$

Lemma 2.3. *The following frame field F_1, F_2, F_3, F_4 defined by*

$$\begin{aligned}F_1 &:= h_A E_1, & F_2 &:= h_A E_2 \\ F_3 &:= h_B E_1 + h_C E_3, & F_4 &:= h_B E_2 + h_C E_4\end{aligned}$$

form an orthonormal frame field on M . And they satisfy the following relations

$$\begin{aligned}[F_1, F_2] &= -\frac{y^2(2Ay + 3Bv^2)}{2(Ay + Bv^2)^2} E_1, & [F_1, F_3] &= 0, \\ [F_1, F_4] &= -\frac{B\sqrt{B} y^{\frac{3}{2}} v^3}{2\sqrt{A} (Ay + Bv^2)^2} E_1, \\ [F_2, F_3] &= \frac{\sqrt{B} y^{\frac{3}{2}} v (Ay + 2Bv^2)}{2\sqrt{A} (Ay + Bv^2)^2} E_1 + \frac{\sqrt{A} y^{\frac{3}{2}}}{2\sqrt{B} (Ay + Bv^2)} E_3,\end{aligned}$$

$$[F_2, F_4] = \frac{\sqrt{B}y^{\frac{3}{2}}v}{2\sqrt{A}(Ay + Bv^2)} E_2 + \frac{\sqrt{A}y^{\frac{3}{2}}}{2\sqrt{B}(Ay + Bv^2)} E_4$$

and

$$[F_3, F_4] = -\frac{2A^2y^3 + 3ABy^2v^2 + 2B^2yv^4}{2A(Ay + Bv^2)^2} E_1 - \frac{3Ayv + 2Bv^3}{2A(Ay + Bv^2)} E_3.$$

Proof. The first statement follows from the Gram-Schmidt orthogonalization process. The proof of the second statement follows from a direct computation. \square

Definition 2.1. Let X and Y be two smooth vector fields on M . The curvature operator $R(X, Y) : \mathcal{X}(M) \rightarrow \mathcal{X}(M)$ is defined as

$$(2.6) \quad R(X, Y)Z := \nabla_X(\nabla_Y Z) - \nabla_Y(\nabla_X Z) - \nabla_{[X, Y]}Z, \quad Z \in \mathcal{X}(M).$$

For a quadruple (X, Y, Z, W) of smooth vector fields on M , we define

$$(2.7) \quad R(X, Y, Z, W) := g(R(X, Y)Z, W).$$

The tensor $R(X, Y, Z, W)$ is called the *Riemann curvature tensor* of M .

3. Sectional curvatures

For any point $p \in M$, we let $\pi_{X, Y}$ be the plane section of tangent space $T_p(M)$ of M at p spanned by two orthonormal tangent vectors X and Y in $T_p(M)$. We recall that the *sectional curvature* $K_p(\pi_{X, Y})$ of $\pi_{X, Y}$ is defined by

$$(3.1) \quad K_p(\pi_{X, Y}) := -R(X, Y, Z, W) = -g(R(X, Y)Z, W),$$

where $R(X, Y, Z, W)$ denotes the Riemann curvature tensor of M . In fact, the sectional curvature $K_p(\pi_{X, Y})$ is independent of the choice of two orthonormal basis of the section $\pi_{X, Y}$.

Theorem 3.1. For any point $p = (x, y, u, v) \in M$, we let π_{ij} the plane section of $T_p(M)$ spanned by two orthonormal vectors F_{ip} and F_{jp} of $T_p(M)$. Then the sectional curvatures $K_p(\pi_{X, Y})$ are given by

$$\begin{aligned} K_p(\pi_{12}) &= -\frac{1}{A} + \frac{3B^2v^4}{2A(Ay + Bv^2)^2}, & K_p(\pi_{13}) &= -\frac{1}{4A}, \\ K_p(\pi_{14}) &= -\frac{1}{4A} + \frac{3AByv^2}{2A(Ay + Bv^2)^2}, & K_p(\pi_{23}) &= -\frac{1}{4A} + \frac{3AByv^2}{2A(Ay + Bv^2)^2}, \\ K_p(\pi_{24}) &= -\frac{1}{4A}, & K_p(\pi_{34}) &= \frac{1}{2A} - \frac{3Bv^2(2Ay + Bv^2)}{2A(Ay + Bv^2)^2}. \end{aligned}$$

Proof. We observe that $K_p(\pi_{ij}) = -g(R(F_{ip}, F_{jp})F_{ip}, F_{jp})$ for $1 \leq i, j \leq 4$. By a direct computation, we obtain

$$\begin{aligned} \nabla_{E_1} \nabla_{E_2} E_1 &= (\Gamma_{11}^2 \Gamma_{12}^1 + \Gamma_{12}^3 \Gamma_{13}^2) E_2 + (\Gamma_{11}^4 \Gamma_{12}^1 + \Gamma_{12}^3 \Gamma_{13}^4) E_4, \\ \nabla_{E_1} \nabla_{E_2} E_2 &= (\Gamma_{12}^1 \Gamma_{22}^2 + \Gamma_{14}^1 \Gamma_{22}^4) E_1 + (\Gamma_{12}^3 \Gamma_{22}^2 + \Gamma_{14}^3 \Gamma_{22}^4) E_3, \end{aligned}$$

$$\begin{aligned}
\nabla_{E_1} \nabla_{E_2} E_3 &= (\Gamma_{11}^2 \Gamma_{23}^1 + \Gamma_{13}^2 \Gamma_{23}^2) E_2 + (\Gamma_{11}^4 \Gamma_{23}^1 + \Gamma_{13}^4 \Gamma_{23}^3) E_4, \\
\nabla_{E_1} \nabla_{E_3} E_1 &= (\Gamma_{12}^1 \Gamma_{13}^2 + \Gamma_{13}^4 \Gamma_{14}^1) E_1 + (\Gamma_{12}^3 \Gamma_{13}^2 + \Gamma_{13}^4 \Gamma_{14}^3) E_3, \\
\nabla_{E_1} \nabla_{E_4} E_1 &= (\Gamma_{11}^2 \Gamma_{14}^1 + \Gamma_{13}^2 \Gamma_{14}^3) E_2 + (\Gamma_{11}^4 \Gamma_{14}^1 + \Gamma_{13}^4 \Gamma_{14}^3) E_4, \\
\nabla_{E_1} \nabla_{E_4} E_3 &= (\Gamma_{11}^2 \Gamma_{12}^1 + \Gamma_{12}^3 \Gamma_{13}^2) E_2 + (\Gamma_{11}^4 \Gamma_{12}^1 + \Gamma_{12}^3 \Gamma_{13}^4) E_4, \\
\nabla_{E_2} \nabla_{E_1} E_1 &= \left(\Gamma_{11}^2 \Gamma_{22}^2 + \Gamma_{11}^4 \Gamma_{24}^2 + \frac{\partial \Gamma_{11}^2}{\partial y} \right) E_2 + \left(\Gamma_{11}^2 \Gamma_{22}^4 + \Gamma_{11}^4 \Gamma_{24}^4 + \frac{\partial \Gamma_{11}^4}{\partial y} \right) E_4, \\
\nabla_{E_2} \nabla_{E_1} E_2 &= \left(\Gamma_{12}^1 \Gamma_{12}^1 + \Gamma_{12}^3 \Gamma_{23}^1 + \frac{\partial \Gamma_{12}^1}{\partial y} \right) E_1 + \left(\Gamma_{12}^1 \Gamma_{12}^3 + \Gamma_{12}^3 \Gamma_{23}^3 + \frac{\partial \Gamma_{12}^3}{\partial y} \right) E_3, \\
\nabla_{E_2} \nabla_{E_1} E_3 &= \left(\Gamma_{13}^2 \Gamma_{22}^2 + \Gamma_{13}^4 \Gamma_{24}^2 + \frac{\partial \Gamma_{13}^2}{\partial y} \right) E_2 + \left(\Gamma_{13}^2 \Gamma_{22}^4 + \Gamma_{13}^4 \Gamma_{24}^4 + \frac{\partial \Gamma_{13}^4}{\partial y} \right) E_4, \\
\nabla_{E_2} \nabla_{E_3} E_2 &= \left(\Gamma_{12}^1 \Gamma_{23}^1 + \Gamma_{32}^1 \Gamma_{23}^3 + \frac{\partial \Gamma_{23}^1}{\partial y} \right) E_1 + \left(\Gamma_{12}^3 \Gamma_{23}^1 + \Gamma_{23}^3 \Gamma_{23}^3 + \frac{\partial \Gamma_{23}^3}{\partial y} \right) E_3, \\
\nabla_{E_2} \nabla_{E_3} E_3 &= \left(\Gamma_{22}^2 \Gamma_{33}^2 + \Gamma_{24}^2 \Gamma_{33}^4 + \frac{\partial \Gamma_{33}^2}{\partial y} \right) E_2 + \left(\Gamma_{22}^4 \Gamma_{33}^2 + \Gamma_{24}^4 \Gamma_{33}^4 + \frac{\partial \Gamma_{33}^4}{\partial y} \right) E_4, \\
\nabla_{E_2} \nabla_{E_4} E_2 &= \left(\Gamma_{22}^2 \Gamma_{24}^2 + \Gamma_{24}^2 \Gamma_{24}^4 + \frac{\partial \Gamma_{24}^2}{\partial y} \right) E_2 + \left(\Gamma_{22}^4 \Gamma_{24}^2 + \Gamma_{24}^4 \Gamma_{24}^4 + \frac{\partial \Gamma_{24}^4}{\partial y} \right) E_4, \\
\nabla_{E_3} \nabla_{E_1} E_1 &= (\Gamma_{11}^2 \Gamma_{23}^1 + \Gamma_{11}^4 \Gamma_{34}^1) E_1 + (\Gamma_{11}^2 \Gamma_{23}^3 + \Gamma_{11}^4 \Gamma_{34}^3) E_3, \\
\nabla_{E_3} \nabla_{E_2} E_1 &= (\Gamma_{12}^1 \Gamma_{13}^2 + \Gamma_{12}^3 \Gamma_{33}^2) E_2 + (\Gamma_{12}^1 \Gamma_{13}^4 + \Gamma_{12}^3 \Gamma_{33}^4) E_4, \\
\nabla_{E_3} \nabla_{E_2} E_2 &= (\Gamma_{22}^2 \Gamma_{23}^1 + \Gamma_{22}^4 \Gamma_{34}^1) E_1 + (\Gamma_{22}^2 \Gamma_{23}^3 + \Gamma_{22}^4 \Gamma_{34}^3) E_3, \\
\nabla_{E_3} \nabla_{E_2} E_3 &= (\Gamma_{13}^2 \Gamma_{23}^1 + \Gamma_{23}^3 \Gamma_{33}^2) E_2 + (\Gamma_{13}^4 \Gamma_{23}^1 + \Gamma_{23}^3 \Gamma_{33}^4) E_4, \\
\nabla_{E_3} \nabla_{E_4} E_1 &= (\Gamma_{13}^2 \Gamma_{14}^1 + \Gamma_{14}^3 \Gamma_{33}^2) E_2 + (\Gamma_{13}^4 \Gamma_{14}^1 + \Gamma_{14}^3 \Gamma_{33}^4) E_4, \\
\nabla_{E_3} \nabla_{E_4} E_3 &= (\Gamma_{13}^2 \Gamma_{34}^1 + \Gamma_{33}^3 \Gamma_{34}^3) E_2 + (\Gamma_{13}^4 \Gamma_{34}^1 + \Gamma_{33}^3 \Gamma_{34}^3) E_4, \\
\nabla_{E_4} \nabla_{E_1} E_1 &= \left(\Gamma_{11}^2 \Gamma_{24}^2 + \Gamma_{11}^4 \Gamma_{44}^2 + \frac{\partial \Gamma_{11}^2}{\partial v} \right) E_2 + \left(\Gamma_{11}^2 \Gamma_{24}^4 + \Gamma_{11}^4 \Gamma_{44}^4 + \frac{\partial \Gamma_{11}^4}{\partial v} \right) E_4, \\
\nabla_{E_4} \nabla_{E_1} E_3 &= \left(\Gamma_{13}^2 \Gamma_{24}^2 + \Gamma_{13}^4 \Gamma_{44}^2 + \frac{\partial \Gamma_{13}^2}{\partial v} \right) E_2 + \left(\Gamma_{13}^2 \Gamma_{24}^4 + \Gamma_{13}^4 \Gamma_{44}^4 + \frac{\partial \Gamma_{13}^4}{\partial v} \right) E_4, \\
\nabla_{E_4} \nabla_{E_2} E_2 &= \left(\Gamma_{22}^2 \Gamma_{24}^2 + \Gamma_{22}^4 \Gamma_{44}^2 + \frac{\partial \Gamma_{22}^2}{\partial v} \right) E_2 + \left(\Gamma_{22}^2 \Gamma_{24}^4 + \Gamma_{22}^4 \Gamma_{44}^4 + \frac{\partial \Gamma_{22}^4}{\partial v} \right) E_4, \\
\nabla_{E_4} \nabla_{E_3} E_3 &= \left(\Gamma_{24}^2 \Gamma_{33}^2 + \Gamma_{33}^4 \Gamma_{44}^2 + \frac{\partial \Gamma_{33}^2}{\partial v} \right) E_2 + \left(\Gamma_{24}^2 \Gamma_{33}^4 + \Gamma_{33}^4 \Gamma_{44}^4 + \frac{\partial \Gamma_{33}^4}{\partial v} \right) E_4.
\end{aligned}$$

Thus according to Lemma 2.2, Lemma 2.3 and the above formulas, we have

$$\begin{aligned}
R(F_1, F_2)F_1 &= -h_A \left\{ \left(h_A \frac{\partial h_A}{\partial y} + \theta_1 \right) \Gamma_{11}^2 + h_A^2 \frac{\partial \Gamma_{11}^2}{\partial y} \right\} E_2 \\
&\quad - h_A \left\{ \left(h_A \frac{\partial h_A}{\partial y} + \theta_1 \right) \Gamma_{11}^4 + h_A^2 \frac{\partial \Gamma_{11}^4}{\partial y} \right\} E_4, \\
R(F_1, F_3)F_1 &= h_A^2 h_C \left\{ (\Gamma_{14}^1 \Gamma_{13}^4 - \Gamma_{11}^4 \Gamma_{34}^1) \right\} E_1 \\
&\quad + h_A^2 h_C \left\{ (\Gamma_{12}^3 \Gamma_{13}^2 + \Gamma_{13}^4 \Gamma_{14}^3 - \Gamma_{11}^2 \Gamma_{32}^3 - \Gamma_{11}^4 \Gamma_{34}^3) \right\} E_3,
\end{aligned}$$

$$\begin{aligned}
R(F_1, F_4)F_1 &= h_A \left\{ h_A h_C \left(\Gamma_{13}^2 \Gamma_{14}^3 - \Gamma_{11}^4 \Gamma_{44}^2 - \frac{\partial \Gamma_{11}^2}{\partial v} \right) \right. \\
&\quad \left. - h_A h_B \frac{\partial \Gamma_{11}^2}{\partial y} - \left(h_B \frac{\partial h_A}{\partial y} + h_C \frac{\partial h_A}{\partial v} + \theta_2 \right) \Gamma_{11}^2 \right\} E_2 \\
&\quad + h_A \left\{ h_A h_C \left(\Gamma_{13}^4 \Gamma_{14}^3 + \Gamma_{11}^4 \Gamma_{14}^1 - \Gamma_{11}^2 \Gamma_{24}^2 - \Gamma_{11}^4 \Gamma_{44}^4 - \frac{\partial \Gamma_{11}^4}{\partial v} \right) \right. \\
&\quad \left. - h_A h_B \frac{\partial \Gamma_{11}^4}{\partial y} - \left(h_B \frac{\partial h_A}{\partial y} + h_C \frac{\partial h_A}{\partial v} + \theta_2 \right) \Gamma_{11}^4 \right\} E_4,
\end{aligned}$$

$$\begin{aligned}
R(F_2, F_3)F_2 &= h_A \left\{ h_A h_C \left(\Gamma_{23}^1 \Gamma_{23}^3 - \Gamma_{22}^4 \Gamma_{34}^1 + \frac{\partial \Gamma_{23}^1}{\partial y} \right) \right. \\
&\quad \left. + \left(h_A h_B \frac{\partial \Gamma_{12}^1}{\partial y} + h_A \frac{\partial h_B}{\partial y} \Gamma_{12}^1 + h_A \frac{\partial h_C}{\partial y} \Gamma_{23}^1 - \theta_3 \Gamma_{12}^1 - \theta_4 \Gamma_{23}^1 \right) \right\} E_1 \\
&\quad + h_A \left\{ h_A h_C \left(\Gamma_{12}^3 \Gamma_{23}^1 + \Gamma_{23}^3 \Gamma_{23}^3 - \Gamma_{22}^2 \Gamma_{23}^3 - \Gamma_{22}^4 \Gamma_{34}^3 + \frac{\partial \Gamma_{23}^3}{\partial y} \right) \right. \\
&\quad \left. + \left(h_A h_B \frac{\partial \Gamma_{12}^3}{\partial y} + h_A \frac{\partial h_B}{\partial y} \Gamma_{12}^3 + h_A \frac{\partial h_C}{\partial y} \Gamma_{23}^3 - \theta_3 \Gamma_{12}^3 - \theta_4 \Gamma_{23}^3 \right) \right\} E_3,
\end{aligned}$$

$$\begin{aligned}
R(F_2, F_4)F_2 &= \left\{ h_A^2 h_C \left(\Gamma_{24}^2 \Gamma_{24}^4 - \Gamma_{22}^4 \Gamma_{44}^2 + \frac{\partial \Gamma_{24}^2}{\partial y} - \frac{\partial \Gamma_{22}^2}{\partial v} \right) \right. \\
&\quad + h_A \left(h_A \frac{\partial h_B}{\partial y} - h_B \frac{\partial h_A}{\partial y} - h_C \frac{\partial h_A}{\partial v} \right) \Gamma_{22}^2 + h_A^2 \frac{\partial h_C}{\partial y} \Gamma_{24}^2 \\
&\quad + h_A \frac{\partial h_A}{\partial y} \frac{\partial h_B}{\partial y} + h_A \frac{\partial h_C}{\partial y} \frac{\partial h_A}{\partial v} - h_B \left(\frac{\partial h_A}{\partial y} \right)^2 - h_C \frac{\partial h_A}{\partial y} \frac{\partial h_A}{\partial v} \\
&\quad \left. - h_A \theta_5 \Gamma_{22}^2 - h_A \theta_4 \Gamma_{24}^2 - \theta_5 \frac{\partial h_A}{\partial y} - \theta_4 \frac{\partial h_A}{\partial v} \right\} E_2 \\
&\quad + \left\{ h_A^2 h_C \left(\Gamma_{22}^4 \Gamma_{24}^2 + \Gamma_{24}^4 \Gamma_{24}^4 + \frac{\partial \Gamma_{24}^4}{\partial y} - \Gamma_{22}^2 \Gamma_{24}^4 - \Gamma_{22}^4 \Gamma_{44}^4 \right. \right. \\
&\quad \left. \left. - \frac{\partial \Gamma_{22}^4}{\partial v} \right) + h_A \left(h_A \frac{\partial h_B}{\partial y} - h_B \frac{\partial h_A}{\partial y} - h_C \frac{\partial h_A}{\partial v} \right) \Gamma_{22}^4 \right. \\
&\quad \left. + h_A^2 \frac{\partial h_C}{\partial y} \Gamma_{24}^4 - h_A \theta_5 \Gamma_{22}^4 - h_A \theta_4 \Gamma_{24}^4 \right\} E_4,
\end{aligned}$$

$$R(F_3, F_4)F_3 = - \left\{ h_B^2 \left(h_B \frac{\partial \Gamma_{11}^2}{\partial y} + h_C \frac{\partial \Gamma_{11}^2}{\partial v} + 2h_C \frac{\partial \Gamma_{13}^2}{\partial y} \right) \right.$$

$$\begin{aligned}
& + h_C^2 \left(h_C \frac{\partial \Gamma_{33}^2}{\partial v} + h_B \frac{\partial \Gamma_{33}^2}{\partial v} + 2h_B \frac{\partial \Gamma_{13}^2}{\partial v} \right) \Big\} E_2 \\
& - \left\{ h_B^2 \left(h_B \frac{\partial \Gamma_{11}^4}{\partial y} + h_C \frac{\partial \Gamma_{11}^4}{\partial v} + 2h_C \frac{\partial \Gamma_{13}^4}{\partial y} \right) \right. \\
& \left. + h_C^2 \left(h_C \frac{\partial \Gamma_{33}^4}{\partial v} + h_B \frac{\partial \Gamma_{33}^4}{\partial v} + 2h_B \frac{\partial \Gamma_{13}^4}{\partial v} \right) \right\} E_4,
\end{aligned}$$

where we put

$$\theta_1 := -\frac{y^2(2Ay + 3Bv^2)}{2(Ay + Bv^2)^2}, \quad \theta_2 := -\frac{B\sqrt{B}y^{\frac{3}{2}}v^3}{2\sqrt{A}(Ay + Bv^2)^2}, \quad \theta_3 := \frac{\sqrt{B}y^{\frac{3}{2}}v(Ay + 2Bv^2)}{2\sqrt{A}(Ay + Bv^2)^2}$$

and

$$\theta_4 := \frac{\sqrt{A}y^{\frac{3}{2}}}{2\sqrt{B}(Ay + Bv^2)}, \quad \theta_5 := \frac{\sqrt{B}y^{\frac{3}{2}}v}{2\sqrt{A}(Ay + Bv^2)}.$$

Using (2.2), (2.5), (2.7), Lemma 2.1, Lemma 2.2 and the above formulas, we obtain the above sectional curvatures $K_p(\pi_{ij})$ for $1 \leq i \leq j \leq 4$. \square

Theorem 3.2. *The scalar curvature $r(p)$ of the Siegel-Jacobi space*

$$(M, ds_{1,1;A,B}^2)$$

is

$$r(p) = -\frac{3}{A} \quad \text{for all } p \in M.$$

Proof. We recall that the scalar curvature $r(p)$ of M is defined as

$$r(p) := \sum_{i,j=1}^4 R(F_{ip}, F_{jp}, F_{jp}, F_{ip}), \quad p \in M.$$

We note that the scalar curvature $r(p)$ is independent of the choice of an orthonormal basis of $T_p(M)$. Since the following symmetry relations

$$R(X, Y)Z + R(Y, X)Z = 0$$

hold for all $X, Y, Z \in \mathcal{X}(M)$, we have

$$\begin{aligned}
r(p) = & -2 \left\{ R(F_{1p}, F_{2p}, F_{1p}, F_{2p}) + R(F_{1p}, F_{3p}, F_{1p}, F_{3p}) \right. \\
& + R(F_{1p}, F_{4p}, F_{1p}, F_{4p}) + R(F_{2p}, F_{3p}, F_{2p}, F_{3p}) \\
& \left. + R(F_{2p}, F_{4p}, F_{2p}, F_{4p}) + R(F_{3p}, F_{4p}, F_{3p}, F_{4p}) \right\}.
\end{aligned}$$

According to Theorem 3.1, we obtain

$$r(p) = -\frac{3}{A}.$$

This completes the proof of the above theorem. \square

Remark 3.1. The Poincaré upper half plane \mathbb{H}_1 is a two dimensional Riemannian manifold with the Poincaré metric

$$ds_0^2 := \frac{dx^2 + dy^2}{y^2}, \quad z = x + iy \in \mathbb{H}_1 \text{ with } x, y \text{ real.}$$

It is easily seen that the Gaussian curvature of (\mathbb{H}_1, ds_0^2) is -1 everywhere and (\mathbb{H}_1, ds_0^2) is an Einstein manifold. Indeed, if we denote by $S_0(X, Y)$ the Ricci curvature of (\mathbb{H}_1, ds_0^2) , then we have

$$S_0(X, Y) = -g_0(X, Y) \quad \text{for all } X, Y \in \mathcal{X}(\mathbb{H}_1),$$

where $g_0(X, Y)$ is the inner product on the tangent bundle $T(\mathbb{H}_1)$ induced by the Poincaré ds_0^2 . But the Siegel-Jacobi space $(\mathbb{H}_1 \times \mathbb{C}, ds_{1,1;1,1}^2)$ is not an Einstein manifold. In fact, if we denote by $S(X, Y)$ the Ricci curvature of the Siegel-Jacobi space $(\mathbb{H}_1 \times \mathbb{C}, ds_{1,1;1,1}^2)$, we can see without difficulty that there does not exist a constant c such that

$$S(E_1, E_1) = c g(E_1, E_1) = c g_{11}.$$

4. Final remarks

Let $\mathbb{D} = \{\zeta \in \mathbb{C} \mid |\zeta| < 1\}$ be the unit disk in the complex plane. We let

$$G_*^J := \left\{ \left(\begin{pmatrix} p & q \\ \bar{q} & \bar{p} \end{pmatrix}, (\xi, \bar{\xi}; i\kappa) \right) \mid \begin{pmatrix} p & q \\ \bar{q} & \bar{p} \end{pmatrix} \in SU(1, 1), \xi \in \mathbb{C}, \kappa \in \mathbb{R} \right\}$$

be the Jacobi group equipped with the multiplication law

$$\begin{aligned} & \left(\begin{pmatrix} p & q \\ \bar{q} & \bar{p} \end{pmatrix}, (\xi, \bar{\xi}; i\kappa) \right) \cdot \left(\begin{pmatrix} p' & q' \\ \bar{q}' & \bar{p}' \end{pmatrix}, (\xi', \bar{\xi}'; i\kappa') \right) \\ &= \left(\begin{pmatrix} p & q \\ \bar{q} & \bar{p} \end{pmatrix} \begin{pmatrix} p' & q' \\ \bar{q}' & \bar{p}' \end{pmatrix}, (\tilde{\xi} + \xi', \tilde{\theta} + \bar{\xi}'; i\kappa + i\kappa' + \tilde{\xi}^t \bar{\xi}' - \tilde{\theta}^t \xi') \right), \end{aligned}$$

where $\tilde{\xi} = p'\xi + \bar{q}'\bar{\xi}$ and $\tilde{\theta} = q'\xi + \bar{p}'\bar{\xi}$. Then G_*^J acts on the Siegel-Jacobi disk $\mathbb{D} \times \mathbb{C}$ transitively by

$$(4.1) \quad \left(\begin{pmatrix} p & q \\ \bar{q} & \bar{p} \end{pmatrix}, (\xi, \bar{\xi}; i\kappa) \right) \cdot (\zeta, \eta) = \left(\frac{p\zeta + q}{\bar{q}\zeta + \bar{p}}, \frac{\eta + \xi\zeta + \bar{\xi}}{\bar{q}\zeta + \bar{p}} \right),$$

where $\zeta \in \mathbb{D}$ and $\eta \in \mathbb{C}$. According to (1.2), we see that $G_{1,1}^J$ acts on $\mathbb{H}_1 \times \mathbb{C}$ transitively by

$$(4.2) \quad \left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}, (\lambda, \mu; \kappa) \right) \cdot (z, w) = \left(\frac{az + b}{cz + d}, \frac{w + \lambda z + \mu}{cz + d} \right),$$

where $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL(2, \mathbb{R})$, $\lambda, \mu, \kappa \in \mathbb{R}$, $z \in \mathbb{H}_1$ and $w \in \mathbb{C}$.

In [15], the author proved that the action (4.1) of G_*^J on the Siegel-Jacobi disk $\mathbb{D} \times \mathbb{C}$ is compatible with the action (4.2) of G_*^J on the Siegel-Jacobi space

$\mathbb{H}_1 \times \mathbb{C}$ via the partial Cayley transform $\Phi_* : \mathbb{D} \times \mathbb{C} \rightarrow \mathbb{H}_1 \times \mathbb{C}$ defined by

$$(4.3) \quad \Phi_*(\zeta, \eta) := \left(\frac{i(1+\zeta)}{1-\zeta}, \frac{2i\eta}{1-\zeta} \right), \quad (\zeta, \eta) \in \mathbb{D} \times \mathbb{C}.$$

Precisely, if $g = \left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}, (\lambda, \mu; \kappa) \right) \in G_{1,1}^J$, we put

$$(4.4) \quad g_* = \left(\left(\frac{p}{\bar{q}} \quad \frac{q}{\bar{p}} \right), \left(\frac{1}{2}(\lambda + i\mu), \frac{1}{2}(\lambda - i\mu); -i\frac{\kappa}{2} \right) \right),$$

where

$$p = \frac{1}{2} \{ (a+d) + i(b-c) \}$$

and

$$q = \frac{1}{2} \{ (a-d) - i(b+c) \}.$$

We note that g_* is an element of G_*^J . The compatibility condition means that the following condition

$$(4.5) \quad g \cdot \Phi_*(\zeta, \eta) = \Phi_*(g_* \cdot (\zeta, \eta)) \quad \text{for all } g \in G_{1,1}^J \text{ and } (\zeta, \eta) \in \mathbb{D} \times \mathbb{C}$$

holds. Using the compatibility condition (4.5), the author [16] proved that for any two positive real numbers A and B ,

$$\begin{aligned} d\tilde{s}_{1,1;A,B}^2 &= 4A \frac{d\zeta d\bar{\zeta}}{(1-|\zeta|^2)^2} \\ &+ 4B \left\{ \frac{d\eta d\bar{\eta}}{1-|\zeta|^2} + \frac{(1+|\zeta|^2)|\eta|^2 - \bar{\zeta}\eta^2 - \zeta\bar{\eta}^2}{(1-|\zeta|^2)^3} d\zeta d\bar{\zeta} \right. \\ &\quad \left. + \frac{\eta\bar{\zeta} - \bar{\eta}}{(1-|\zeta|^2)^2} d\zeta d\bar{\eta} + \frac{\bar{\eta}\zeta - \eta}{(1-|\zeta|^2)^2} d\bar{\zeta} d\eta \right\} \end{aligned}$$

is a Riemannian metric on the Siegel-Jacobi disk $\mathbb{D} \times \mathbb{C}$ which is invariant under the action (4.1) of G_*^J on $\mathbb{D} \times \mathbb{C}$. According to Theorem 1.4 in [16], we see that the Laplace-Beltrami operator $\tilde{\Delta}_{1,1;A,B}$ of the Siegel-Jacobi disk $(\mathbb{D} \times \mathbb{C}, d\tilde{s}_{1,1;A,B}^2)$ is given by

$$\begin{aligned} \tilde{\Delta}_{1,1;A,B} &= \frac{1}{A} \left\{ (1-|\zeta|^2)^2 \frac{\partial^2}{\partial\zeta\partial\bar{\zeta}} + (1-|\zeta|^2)(\eta - \bar{\eta}\zeta) \frac{\partial^2}{\partial\zeta\partial\bar{\eta}} \right. \\ &\quad + (1-|\zeta|^2)(\bar{\eta} - \eta\bar{\zeta}) \frac{\partial^2}{\partial\bar{\zeta}\partial\eta} \\ &\quad \left. + (|\eta|^2 + |\zeta\eta|^2 - \bar{\zeta}\eta^2 - \zeta\bar{\eta}^2) \frac{\partial^2}{\partial\eta\partial\bar{\eta}} \right\} \\ &+ \frac{1}{B} (1-|\zeta|^2) \frac{\partial^2}{\partial\eta\partial\bar{\eta}}. \end{aligned}$$

Theorem 4.1. *The scalar curvature of the Siegel-Jacobi disk $(\mathbb{D} \times \mathbb{C}, d\tilde{s}_{1,1;A,B}^2)$ is*

$$r(q) = -\frac{3}{A} \quad \text{for all } q \in \mathbb{D} \times \mathbb{C}.$$

Proof. The proof follows from Theorem 3.2 and the compatibility condition (4.5). \square

References

- [1] R. Berndt and R. Schmidt, *Elements of the Representation Theory of the Jacobi Group*, Progress in Mathematics, **163**, Birkhäuser, Basel, 1998.
- [2] W. Boothby, *An Introduction to Differentiable Manifolds and Riemannian Geometry*, Academic Press, 1975.
- [3] M. Eichler and D. Zagier, *The Theory of Jacobi Forms*, Progress in Mathematics, **55**, Birkhäuser, Boston, Basel and Stuttgart, 1985.
- [4] E. Kähler, *Mathematische Werke/Mathematical Works*, Edited by R. Berndt and O. Riemenschneider, Walter de Gruyter, Berlin-New York, 2003.
- [5] J. Kramer, *A geometrical approach to the theory of Jacobi forms*, Compositio Math. **79** (1991), no. 1, 1–19.
- [6] ———, *An arithmetic theory of Jacobi forms in higher dimensions*, J. Reine Angew. Math. **458** (1995), 157–182.
- [7] B. Runge, *Theta functions and Siegel-Jacobi forms*, Acta Math. **175** (1995), no. 2, 165–196.
- [8] M. Spivak, *A Comprehensive Introduction to Differential Geometry*, Publish or Perish, Inc., Berkeley, Vol. II, 1979.
- [9] J.-H. Yang, *The Siegel-Jacobi operator*, Abh. Math. Sem. Univ. Hamburg **63** (1993), 135–146.
- [10] ———, *Singular Jacobi forms*, Trans. Amer. Math. Soc. **347** (1995), no. 6, 2041–2049.
- [11] ———, *Construction of vector valued modular forms from Jacobi forms*, Canadian J. Math. **47** (1995), no. 6, 1329–1339.
- [12] ———, *The method of orbits for real Lie groups*, Kyungpook Math. J. **42** (2002), no. 2, 199–272.
- [13] ———, *A note on a fundamental domain for Siegel-Jacobi space*, Houston J. Math. **32** (2006), no. 3, 701–712.
- [14] ———, *Invariant metrics and Laplacians on Siegel-Jacobi space*, J. Number Theory **127** (2007), no. 1, 83–102.
- [15] ———, *A partial Cayley transform for Siegel-Jacobi disk*, J. Korean Math. Soc. **45** (2008), no. 3, 781–794.
- [16] ———, *Invariant metrics and Laplacians on Siegel-Jacobi disk*, Chinese Ann. Math. Ser. B **31** (2010), no. 1, 85–100.
- [17] ———, *Invariant differential operators on Siegel-Jacobi space*, arXiv:1107.0509 v1 [math.NT] 4 July 2011.
- [18] C. Ziegler, *Jacobi forms of higher degree*, Abh. Math. Sem. Univ. Hamburg **59** (1989), 191–224.

JAE-HYUN YANG
 DEPARTMENT OF MATHEMATICS
 INHA UNIVERSITY
 INCHEON 402-751, KOREA
E-mail address: `jhyang@inha.ac.kr`

YOUNG-HOON YONG
GRADUATE SCHOOL OF MATHEMATICS EDUCATION
INHA UNIVERSITY
INCHEON 402-751, KOREA
E-mail address: yyh0302@hanmail.net

SU-NA HUH
GRADUATE SCHOOL OF MATHEMATICS EDUCATION
INHA UNIVERSITY
INCHEON 402-751, KOREA
E-mail address: soonassi@hanmail.net

JUNG-HEE SHIN
GRADUATE SCHOOL OF MATHEMATICS EDUCATION
INHA UNIVERSITY
INCHEON 402-751, KOREA
E-mail address: sjhee1031@hanmail.net

GIL-HONG MIN
GRADUATE SCHOOL OF MATHEMATICS EDUCATION
INHA UNIVERSITY
INCHEON 402-751, KOREA
E-mail address: segeromin@paran.com